

# Markov Chains

## Basics

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```
In[1]:= MarkovStep[K_, s_] := RandomChoice[K[[s]] -> Range[Dimensions[K][[2]]]]
MarkovChain[K_, s_, t_] := NestList[MarkovStep[K, #] &, s, t] (* A sample of t
steps from a Markov chain with transition matrix K starting from state s *)

In[3]:= TransitionsOf[K_] := Flatten[Table[If[K[[i, j]] > 0, i -> j, {}],
{i, Dimensions[K][[1]]}, {j, Dimensions[K][[2]]}]
(* The edges of the directed graph of probable transitions
associated to the transition matrix K *)
```

## Examples

```
In[4]:= RWC5 = 
$$\begin{pmatrix} 0 & 0.5 & 0 & 0 & 0.5 \\ 0.5 & 0 & 0.5 & 0 & 0 \\ 0 & 0.5 & 0 & 0.5 & 0 \\ 0 & 0 & 0.5 & 0 & 0.5 \\ 0.5 & 0 & 0 & 0.5 & 0 \end{pmatrix};$$
 (* Simple random walk on C5 *)
```

```

$$K_1 = \begin{pmatrix} 0.4 & 0.3 & 0 & 0 & 0.3 \\ 0.5 & 0 & 0.4 & 0.1 & 0.0 \\ 0 & 0.5 & 0 & 0.5 & 0 \\ 0.1 & 0 & 0.5 & 0 & 0.4 \\ 0.4 & 0.1 & 0 & 0.5 & 0 \end{pmatrix};$$

```

## Visualization

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### Active State

```
In[6]:= ActiveStateStyle[x_] := {_ -> Gray, x -> Yellow}
MarkovActivePlot[K_, x_] :=
Graph[TransitionsOf[K], VertexStyle -> ActiveStateStyle[x], VertexSize -> Medium]
```

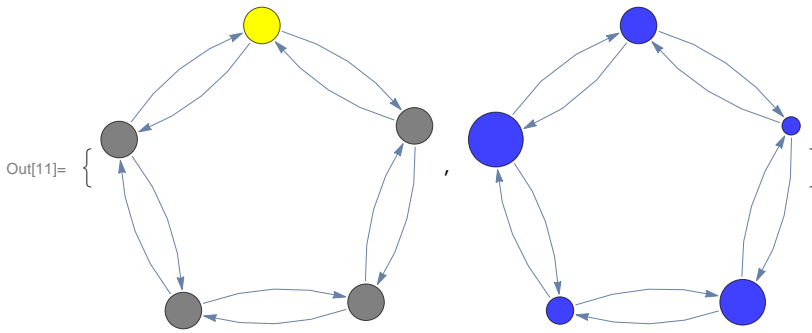
### Distribution

```
In[8]:= DistributionStateStyle[u_] := Table[i -> u[[i]], {i, 1, Length[u]}]
MarkovDistributionPlot[K_, u_] := Graph[TransitionsOf[K],
VertexStyle -> RGBColor[0.25, 0.25, 1], VertexSize -> DistributionStateStyle[u]]
```

### Example

```
In[10]:= u = {0.1, 0.2, 0.3, 0.15, 0.25};
```

```
In[11]:= {MarkovActivePlot[RWC5, 2], MarkovDistributionPlot[RWC5, u]}
```



## Evolution

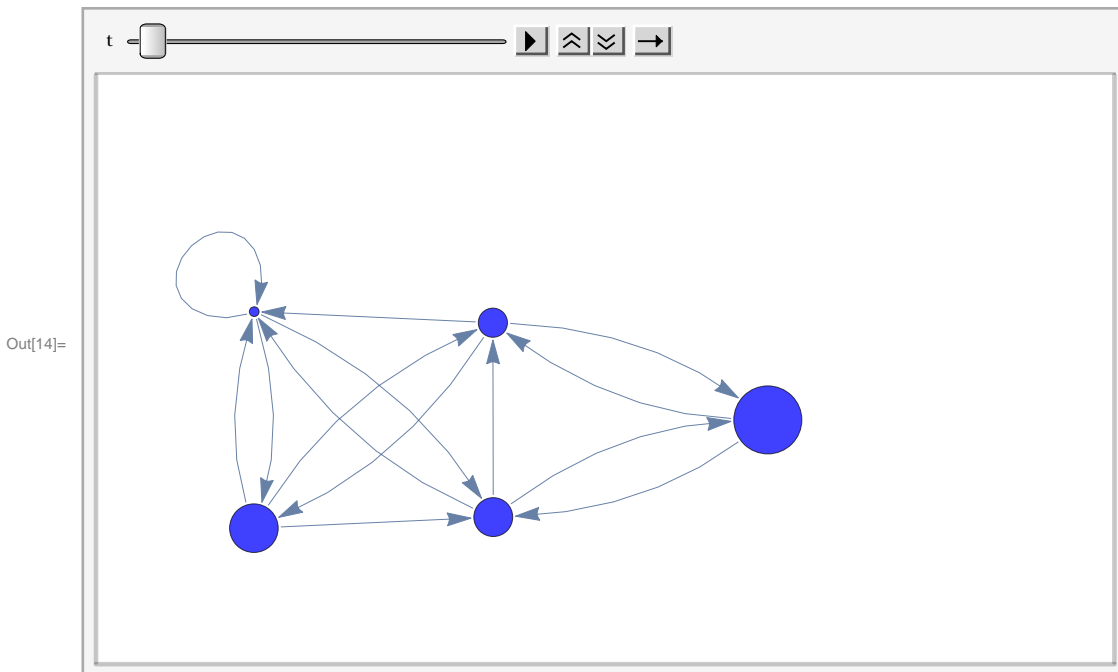
### Evolution of the distribution

```
In[12]:= u = {0.05, 0.2, 0.35, 0.15, 0.25};
```

Random walk on  $C_5$

$K_1$

```
In[14]:= Animate[MarkovDistributionPlot[K1, u.MatrixPower[K1, t]], {t, 0, 100, 1},
  AnimationRunning → False, AnimationRepetitions → 1, AnimationRate → 4]
```



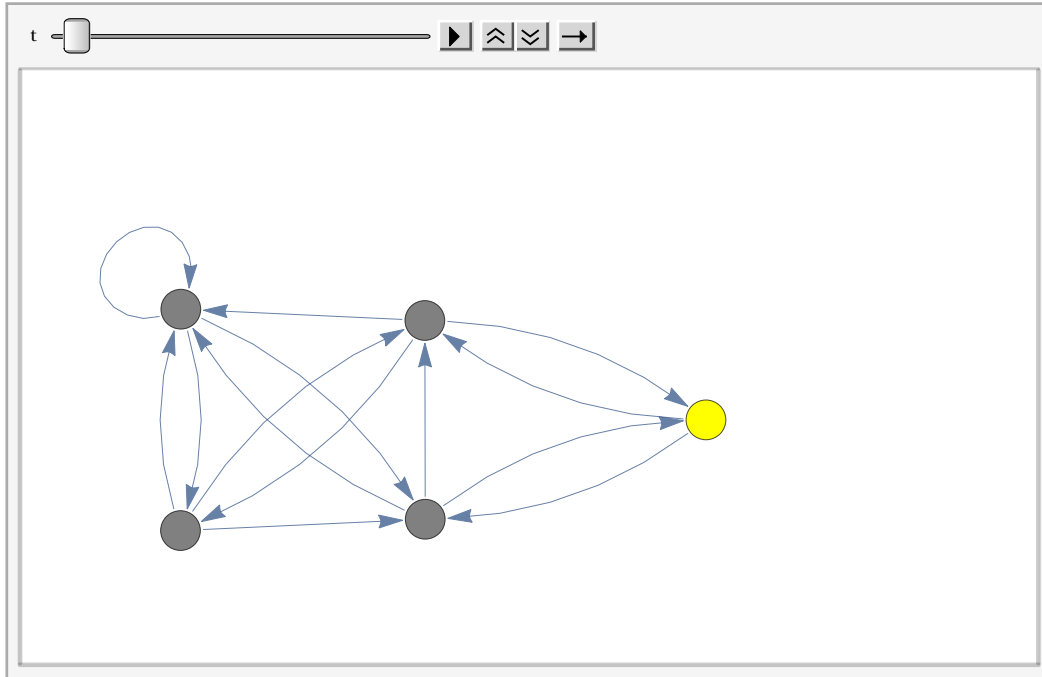
### Evolution of the state

Random walk on  $C_5$

$K_5$ 

```
In[19]:= X0 = 3; (* Initial state *)  
T = 100; (* Number of time steps *)  
X = MarkovChain[K1, X0, T];  
Animate[MarkovActivePlot[K1, X[[t+1]]], {t, 0, T-1, 1},  
  AnimationRunning → False, AnimationRepetitions → 1, AnimationRate → 5]
```

Out[22]=



## Evolution of empirical distribution

Random walk on  $C_5$

K<sub>5</sub>

```

In[30]:= u0 = {1, 0, 0, 0, 0}; (* Distribution of the initial state *)
T = 100; (* Number of time steps *)
n = 1000; (* Number of independent samples *)
XS0 = RandomChoice[u0 → Range[Length[u0]], n]; (* n independent samples from u0 *)
XS = Table[MarkovChain[K1, XS0[[k]], T], {k, 1, n}];
h = Table[Normalize[
  BinCounts[Transpose[XS][[t + 1]], {0.5, Length[u0] + 0.5, 1}], Total], {t, 0, T - 1}];
(* Empirical distribution of n independent runs in T consecutive steps *)
Animate[MarkovDistributionPlot[K1, h[[t + 1]]], {t, 0, T - 1, 1},
  AnimationRunning → False, AnimationRepetitions → 1, AnimationRate → 4]

```

Out[36]=

